CSAW ESC Final - Report

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I. INTRODUCTION

A. Context

This report is about our team, Hackcess, qualifying for the CSAW ECS 2024 finals. We were excited to be named finalists, and we received the Arduino board and other components, officially starting the competition.

B. Objectives

In this report, we will share our achievements in the various challenges we faced over four (4) weeks, which were very various.

C. Hardware and tools

Here is the list of equipment we had:

- Arduino Uno R3 board
- AC/DC Power supply
- Motor shield L293D 4
- Fan motor
- Servo motor
- Stepper motor

The Arduino Uno R3 board was faulty, so we had to replace it with another one, which caused a slight delay.

II. CHALLENGES WEEK 1 A. Normal or Though

The first challenge was called "Normal or Though" and its description was:

"You decided to go to a pub in New York named "Normal Or Though" in the upper west side, a quality restaurant. You hope to have great food based on a quirky recommendation. You were told to order a peculiar food that rarely anyone orders, but the waiter brings you the food after only one minute, and you are surprised by the quick response. As soon as you finish your food, the waiter gives you an arduino, for you to pay and give a quality review. The waiter leaves and you notice that you are the only one left in a quiet room. Then you have a realization... "

After completing the "hardware test," we received the command line to upload a ".hex" (fig1) file to the board. When we uploaded the hex files of the challenge, we noticed that only the fan motor was functioning.

We also noticed that the electric pulsations of the fan motor sounded like Morse code.

"/home/gmx/.arduino15/packages/arduino/tools/avrdude/6.3.0-arduino17/bin/avrdude"
"-C/home/gmx/.arduino15/packages/arduino/tools/avrdude/6.3.0-arduino17/etc/avrdude.conf"
-v -patmega328p -carduino "-P/dev/ttyACM0" -b115200 -D "-Uflash:w:./NormalOrThough.hex:1"

fig 1 : command to upload hex code.

First, we transcribed the pulsations of the fan motor into Morse code (fig2)



fig 2 : Binary serial

then, we transcribed morse code into alphabet, it seems this message. (fig3)

GE2<u>EUDEE;CEÐ</u>+EÐ ERTEEQ52 ÖG.SCI_4NNMIEÖÑAOD CHKBPT TXÉ6E? A) RSP W'EIC <u>D_JI</u> K: :0 S4 TQV <mark>E</mark>AÐI.TJ RFEÖRPH ERÄ CHJI

fig 3 : transcription

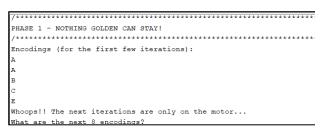
We were stuck here for the first challenge because we did not find any other clues.

B. Friendly Disposition

The second challenge of the first week was called: "Friendly Disposition" and its description was:

"In the heart of a bustling metropolis, a renowned cybersecurity firm, The Sequence Syndicate, has been tasked with securing the city's critical infrastructure against a series of sophisticated cyber-attacks. The attackers. known only as Malicious Disposition, have left behind a trail of encrypted messages that seem to follow mysterious patterns. Decode the sequences and figure out what message the attackers are trying to communicate. "

1. First phase: "Nothing golden can stay"





After looking for the eight encodings with angles, we noticed that the first five letters of the given sequence resembled a Fibonacci sequence.

М	N	0	Р	Q	R
given sequence	Α	Α	в	С	Е
fibonacci	1	1	2	3	5

Fig 5 : letters and fibonnacci

The value of the Fibonacci sequence corresponds to a letter of the alphabet referring by its place. When we exceed 26, we subtract 26 from that value as many times as necessary to get back under 26.

The servo motor completed 16 iterations, and we used our modified Fibonacci algorithm to determine the height next iterations.

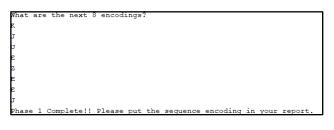


Fig 6: Phase 1 completed

sequence : KJUEZEEJ

2. Second phase : "EXTREME ACCOUNTABLILITY"

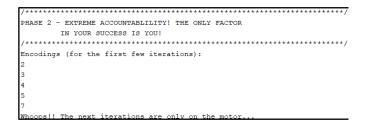


fig 7: phase 2

in the next phase, another sequence was given. This sequence was composed with 5 digits. We tried the Fibonacci algorithm in this second phase, but it did not match the "logic" of the sequence. Then, we attempted other known sequences such as squares, prime numbers, arithmetic, and perfect numbers. Unfortunately, we were unable to match or understand the second phase. We are only certain that the 16 encodings consist of 0 to 9 digits.

III. CHALLENGES WEEK 2 A. KeyRing 1

In this challenge, we had to classify samples from a microphone and a vibration sensor from a key manufacturing site. We also had a bunch of "labeled" files which were already classified to help us. Each key type is labeled A,B,C or D, our first task was to discover the key type of every unclassified samples by using the mp3 and CSV files produced by the sensors.

This could have been easily done using a program allowing the files to be sorted by comparing them to those already classified. Which we did. However an error prevented the program from working on our computers, we did not get any results.

B. KeyRing 2

For the Keyring2, we had to find a key that does not match any of the samples we had in the previous challenge. By analyzing the mp3, csv and stl files, we could have found matches between vibrations, sounds and the shape of the key given in the stl file. A program would have been able to recreate a 3D model approaching what could have been produced at this moment. But we only have this theory.

IV. CHALLENGES WEEK 3 A. Fast&Max

the resumed statement of this challenge:

In a bustling downtown, a bank conceals a treasure in a secret chamber protected by two sophisticated safes. A group of 17 thieves, Fast&Max, aims to break in. To unlock the first safe, they need a 16-digit employee ID encrypted with RSA-like encryption. The second safe requires a cleverly crafted alphabetic PIN to access the hidden treasures.

We have noticed that reverse engineering was allowed for this challenge.

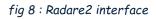
We looked at what the servo motor and the serial monitor were doing. We saw that it sent the ID numbers of an employee that were encrypted with an RSA-like key, and that the serial monitor sent 4 digits at a time that we needed to retrieve.

we disassembled the code using "Radare2,

srec_cat FastMax_Dummy.hex -Intel -o
FastMax_Dummy.bin -Binary

then we opened the FastMax_Dummy.bin file in Radare2





r2 - A FastMax_Dummy.bin

Once in Radare2, this command lists all functions found in the binary file, allowing us to see entry points and potential code sections for analysis. We observed the servo motor's angles while it displayed ID numbers: 1-4 between 75° and 150°, 5-8 between 0° and 75°, 9-12 again between 75° and 150, and 13-16 between 0° and 75°. The angles varied significantly in each range. Despite attempts to identify repeating sequences or transformations, we found no conclusive results. We hypothesize that the servo motor may communicate in Morse code.

V. CHALLENGES WEEK 4 A. Safe cracker 1

For the safe cracker, I had an ino file allowing me to understand how the challenge worked. I understood thanks to it that the first code would necessarily use the single mode. Then, I looked at the demo audio file. I understood that it reproduced a sequence of a value of 100 2 times in each of the modes following the following model: single, single, double, double, interleaved, interleaved, microstep, microstep.

README.md	Update README.md
Safecracker1.mp3	Adding Week 4 Challeng
Safecracker2.mp3	Adding Week 4 Challeng
SafecrackerDemo.mp3	Adding Week 4 Challeng
🗅 musicbox.jpg	Adding Week 4 Challeng
safecracker_release.ino	Adding Week 4 Challeng
safecracker_verify.hex	Adding Week 4 Challeng
🗅 shop.jpg	Week 4 README update

fig 9 : tools and files for safe cracker

Thanks to this file, I was therefore interested in the value of 100 in single mode and I discovered that it lasted about 3.15s. Then, I was able to look at the safecracker audio file in order to carry out the analysis of the audio file and to make the cross product so that I could know what sequence I had to put in the serial monitor. screen result python program, python program also and serial monitor result.

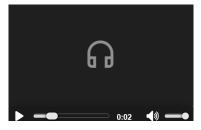


fig 10 : Audio file

Then, when I tried to put them, it told me that it was not the right one. However, being relatively confident about the code produced, I created a program trying each combination at -2, +2 around the value that my first program gave by sending them to the serial monitor and getting back what was written in it.

•	
	<pre>def test_all_combinations():</pre>
	<pre>ser = serial.Serial('COM9', 115200, timeout=1)</pre>
	<pre>time.sleep(2) # Wait for the serial connection to initialize</pre>
	time.sleep(10)
	previous_response = ""
	# Open the file in append mode
13 14	with open("serial_output.txt", "a") as file:
14 15	
	# Function to read and print all lines from the serial until no new line is received def read serial():
	nonlocal previous response
18	while True:
	response = ser.readline().decode().strip()
	if response and response != previous_response:
	print(f"Received: {response}")
	<pre>file.write(f"Received: {response}\n")</pre>
	previous_response = response
	read_serial()
	time.sleep(10)
	for first_value in range(130, 133):
	for second_value in range(89, 93):
	for third_value in range(5, 10):
	<pre>message = f"1 {first_value}S {second_value}S {third_value}S"</pre>
	<pre>ser.write(message.encode())</pre>
	<pre>print(f"Sent: (message)")</pre>
	<pre>file.write(f"Sent: {message}\n")</pre>
	time.sleep(16) # Give some time for Arduino to respond
	read_serial()
	ser.close()
	<pre>ifname == "main": test_all_combinations()</pre>

fig 11 : brute force python code

After 4 hours of testing, the program gave me a text file with the corresponding sequence. I was able to discover that the program had found the right sequence, and I restarted a serial monitor to check it.

			<pre>sers/mathi/AppData/Local uments/R3.09/CSAW/week4.</pre>	
Analyse de	Safecracker1.mp3			
Rotation 1:	Durée: 4.2119375000	secondes		
Valeur arro	ndie: 132			
Rotation 2:	Durée: 2.9446875000	secondes		
Valeur arro	ndie: 92			
Rotation 3:	Durée: 0.2473125000	secondes		
Valeur arro	ndie: 8			
Étapes déte	ctées dans Safecrack	er1.mp3: [132, 9	92, 81	
Modes détec	tés dans Safecracker	1.mp3: ['S', 'S	· · · s· 1	
	cracker1: [132, 92, 1			
finis				

fig 12 : running brute force python file

fig 13 : safe cracker 1 completed

correct combo: 131 92 7

VI. CONCLUSION

In conclusion, throughout this month of challenges, we have significantly enhanced our skills in cybersecurity and logical thinking. This experience has been a valuable opportunity for growth and learning.

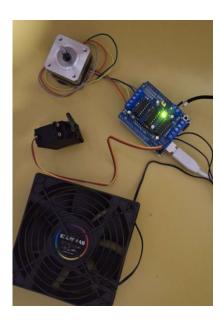


fig 14 : Our setup